

Formal RT solvers

- Long characteristics (Feautrier scheme)
[Cannon C.J. 1970, *Astrophys. J.*, v.161, p.255](#)
- Short characteristics (Attenuation operator)
[Bruls et al. 1999, *Astron. and Astroph.*, v.348, p.233](#)
- Short characteristics (Hermitian scheme)
[Bellot Rubio et al. 1998, *Astrophys. J.*, v.506, p.805](#)

Why formal solver?

- Once we found the source function we need find the intensities in order to compute the energy transport
- The intensities are needed to compute self-consistent level populations → opacities → optical depth scale
- To get a consistent solution we may need to iterate

Requirements for a formal solver

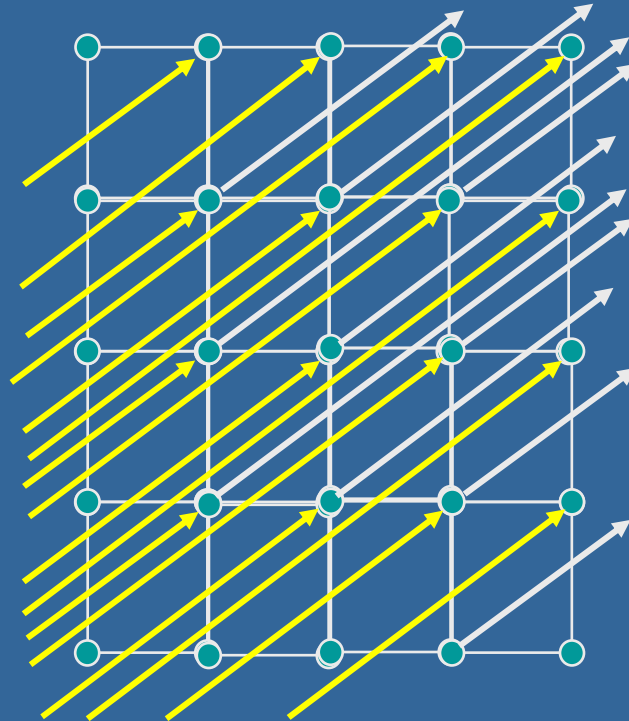
- The solver for intensities must be very quick and stable. It should be able to achieve good accuracy in the prescribed grid on which the source function is known
- The method should not propagate/amplify errors which may occur in early iterations
- The last two requirements make impossible to use RK in NLTE and significant scattering

Method classification

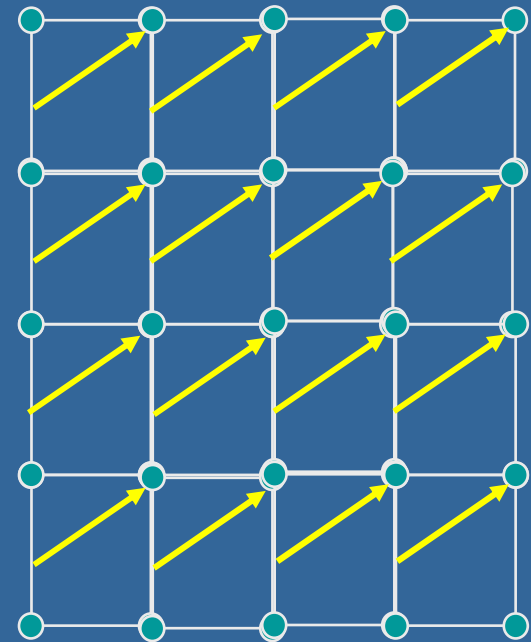
- RT solvers act along rays or *characteristics* that do not necessarily coincide with the selected grid.
- Individual ray can be followed through the whole medium boundary-to-boundary or over a short part extending the length of one grid cell.
- RT solvers based on complete rays are known as *long characteristics* methods.
- RT solvers that follow radiation through a single cell at a time are called *short characteristics* methods.
- In 1D there is obviously no difference between short and long characteristic methods

Method classification

Long characteristics



Short characteristics



Feautrier RT solver

- Equation of radiative transfer (again)

$$\frac{dI_\nu}{dx} = -k_\nu \rho \cdot (I_\nu - S_\nu)$$

where x is a geometrical distance along the ray

- Let's split the intensity in two flows: I^+ in the direction of increasing x and I^- in the opposite direction. The RT equation can be written for each direction:

$$\frac{dI_\nu^+}{dx} = -k_\nu \rho \cdot (I_\nu^+ - S_\nu)$$

$$-\frac{dI_\nu^-}{dx} = -k_\nu \rho \cdot (I_\nu^- - S_\nu)$$

We define two new variables $U = \frac{1}{2}(I^+ + I^-)$ and $V = \frac{1}{2}(I^+ - I^-)$. Now we can add/subtract the two equations of RT and divide the results by 2:

$$\frac{dI_v^+}{dx} = -k_v \rho \cdot (I_v^+ - S_v)$$

+

$$\frac{dI_v^-}{dx} = k_v \rho \cdot (I_v^- - S_v)$$

$$\frac{dU_v}{dx} = -k_v \rho \cdot V_v$$

$$\frac{dI_v^+}{dx} = -k_v \rho \cdot (I_v^+ - S_v)$$

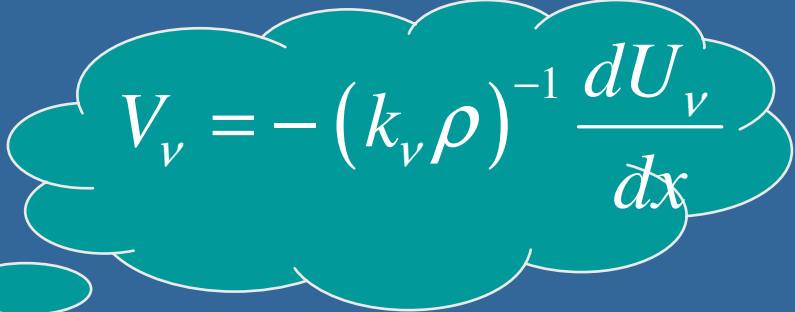
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$$\frac{dI_v^-}{dx} = k_v \rho \cdot (I_v^- - S_v)$$

$$\frac{dV_v}{dx} = -k_v \rho \cdot (U_v - S_v)$$

2nd order form of RT

- We substitute the derivative of V in the 2nd equation using the expression for V from the 1st equation:


$$V_v = - (k_v \rho)^{-1} \frac{dU_v}{dx}$$


$$\frac{dV_v}{dx} = -k_v \rho \cdot (U_v - S_v)$$

- The equations for U and V can be combined to a single 2nd order ODE:

$$\frac{d}{dx} \left[(k_v \rho)^{-1} \frac{dU_v}{dx} \right] = k_v \rho \cdot (U_v - S_v)$$

Boundary Conditions

Boundary conditions are set in the two ends of the medium. For the smallest x we can write:

$$\begin{aligned} (k_v \rho)^{-1} \frac{dU_v}{dx} \Big|_A &= -V_v = -\frac{1}{2}(I_v^+ - I_v^-) = \\ &= \frac{1}{2}(I_v^+ + I_v^-) - I_v^+ = U_v - I_v^A \end{aligned}$$

For the opposite end we have:

$$\begin{aligned} (k_v \rho)^{-1} \frac{dU_v}{dx} \Big|_B &= -V_v = -\frac{1}{2}(I_v^+ - I_v^-) = \\ &= -\frac{1}{2}(I_v^+ + I_v^-) + I_v^- = -U_v + I_v^B \end{aligned}$$

Finite differences equation have familiar form
(note the sign change):

$$-a_i U_{i-1} + b_i U_i - c_i U_{i+1} = d_i \quad \text{for } i = 2, \dots, N-1$$

$$a_i = \frac{1}{x_{i+1} - x_{i-1}} \cdot \frac{\left(k_{v,i}\rho\right)^{-1} + \left(k_{v,i-1}\rho\right)^{-1}}{x_i - x_{i-1}}$$

$$c_i = \frac{1}{x_{i+1} - x_{i-1}} \cdot \frac{\left(k_{v,i+1}\rho\right)^{-1} + \left(k_{v,i}\rho\right)^{-1}}{x_{i+1} - x_i}$$

$$b_i = a_i + c_i + k_{v,i}\rho$$

$$d_i = k_{v,i}\rho \cdot S_{v,i}$$

For $i=1$ we can write linear boundary condition:

$$\frac{U_2 - U_1}{\tau_2 - \tau_1} \approx \left. \frac{dU}{d\tau} \right|_{\tau_{1\frac{1}{2}}} !$$

$$U_{1\frac{1}{2}} = \frac{U_2 - U_1}{2} \approx U_1 + \frac{(\tau_2 - \tau_1)}{2} \cdot \left. \frac{dU}{d\tau} \right|_1 =$$

$$= U_1 + \frac{(\tau_2 - \tau_1)}{2} \cdot (U_1 + I^A)$$

$$\frac{(\tau_2 - \tau_1)}{2} \approx \frac{(k_2 \rho + k_1 \rho)}{2} \cdot \frac{x_2 - x_1}{2}$$

$$U_1 \cdot \left[1 + \frac{(k_2 \rho + k_1 \rho)}{2} \cdot (x_2 - x_1) \right] - 1 \cdot U_2 =$$

$\xrightarrow{b_1} \quad \quad \quad \xrightarrow{c_1} \quad \quad \quad \xrightarrow{d_1}$

$$= \frac{(k_2 \rho + k_1 \rho)}{2} \cdot (x_2 - x_1) \cdot I^A$$

... or we can write quadratic boundary condition:

$$U_2 = U_1 + \delta\tau \left. \frac{dU}{d\tau} \right|_{\tau_1} + \frac{1}{2} \delta\tau^2 \left. \frac{d^2U}{d\tau^2} \right|_{\tau_1} + \dots \approx$$

$$\approx U_1 + \delta\tau \cdot (U_1 - I_v^A) + \frac{1}{2} \delta\tau^2 \cdot (U_1 - S_1)$$

$$\delta\tau \approx \frac{(k_2\rho + k_1\rho)}{2} \cdot (x_2 - x_1)$$

$$U_1 \cdot \left[1 + \delta\tau + \frac{1}{2} \delta\tau^2 \right] - 1 \cdot U_2 =$$

$\xrightarrow{b_1}$
 $\xrightarrow{c_1}$
 $\xrightarrow{d_1}$

$$= \delta\tau \cdot I^A + \frac{1}{2} \delta\tau^2 S_1$$

The case of $i=N$ is similar

For semi-infinite medium boundary
condition at ∞ looks a bit different:

$$\left\{ \begin{array}{l} \frac{dU_v}{d\tau} = U_v - I_v^+ \\ \frac{dI_v^+}{d\tau} = S_v - I_v^+ \\ \lim_{x \rightarrow \infty} I_v^+ = S_v \end{array} \right. \Rightarrow I_v^+ \Big|_{\text{deep}} = S_v + \frac{dS_v}{d\tau} \Rightarrow U_v - \frac{dU_v}{d\tau} = S_v + \frac{dS_v}{d\tau}$$

$$c_1 = \frac{1}{\delta\tau} - \frac{1}{2}$$

$$b_1 = \frac{1}{\delta\tau} + \frac{1}{2}$$

$$d_1 = \frac{1}{2}(S_{v,2} + S_{v,1}) + \frac{(S_{v,2} - S_{v,1})}{\delta\tau}$$

Attenuation operator solver

- Solution of RT over one grid cell can be written:

$$I_{\nu}(\tau_{i+1}) = e^{-(\tau_{i+1} - \tau_i)} \cdot I_{\nu}(\tau_i) + \int_{\tau_i}^{\tau_{i+1}} S_{\nu}(t) \cdot e^{-(\tau_{i+1} - t)} dt$$

where τ is the optical path along the ray

- Suppose S slowly changes with τ which can be approximated by a linear function. Then we can take the integral analytically!

$$S_{\nu}(\tau) = \left[\frac{(\tau_{i+1} - \tau)}{(\tau_{i+1} - \tau_i)} S_{\nu,i} + \frac{(\tau - \tau_i)}{(\tau_{i+1} - \tau_i)} S_{\nu,i+1} \right]$$

$$I_{\nu}(\tau_{i+1}) = I_{\nu}(\tau_i) \cdot e^{-(\tau_{i+1} - \tau_i)} + \eta_{\nu,i}$$

How this works?

- Select direction
- For starting grid points incoming intensity is given by boundary conditions
- To compute the opacity and the source function in the starting and the following points we may need to interpolate. These are needed to compute the intensity in the next point
- One can take 3 points and make parabolic fit to the source function

Hermitian method

Taylor expansion for intensity in point τ_i :

$$I_{i+1} = I_i + \sum_{n=1}^4 \frac{\delta_i^n}{n!} \frac{d^n I}{d \tau^n}$$

$$I' = \frac{dI}{d\tau} + \delta_i \frac{d^2 I}{d\tau^2} + \frac{1}{2} \delta_i^2 \frac{d^3 I}{d\tau^3} + \frac{1}{6} \delta_i^3 \frac{d^4 I}{d\tau^4}$$

$$I'' = \frac{d^2 I}{d\tau^2} + \delta_i \frac{d^3 I}{d\tau^3} + \frac{1}{2} \delta_i^2 \frac{d^4 I}{d\tau^4}$$

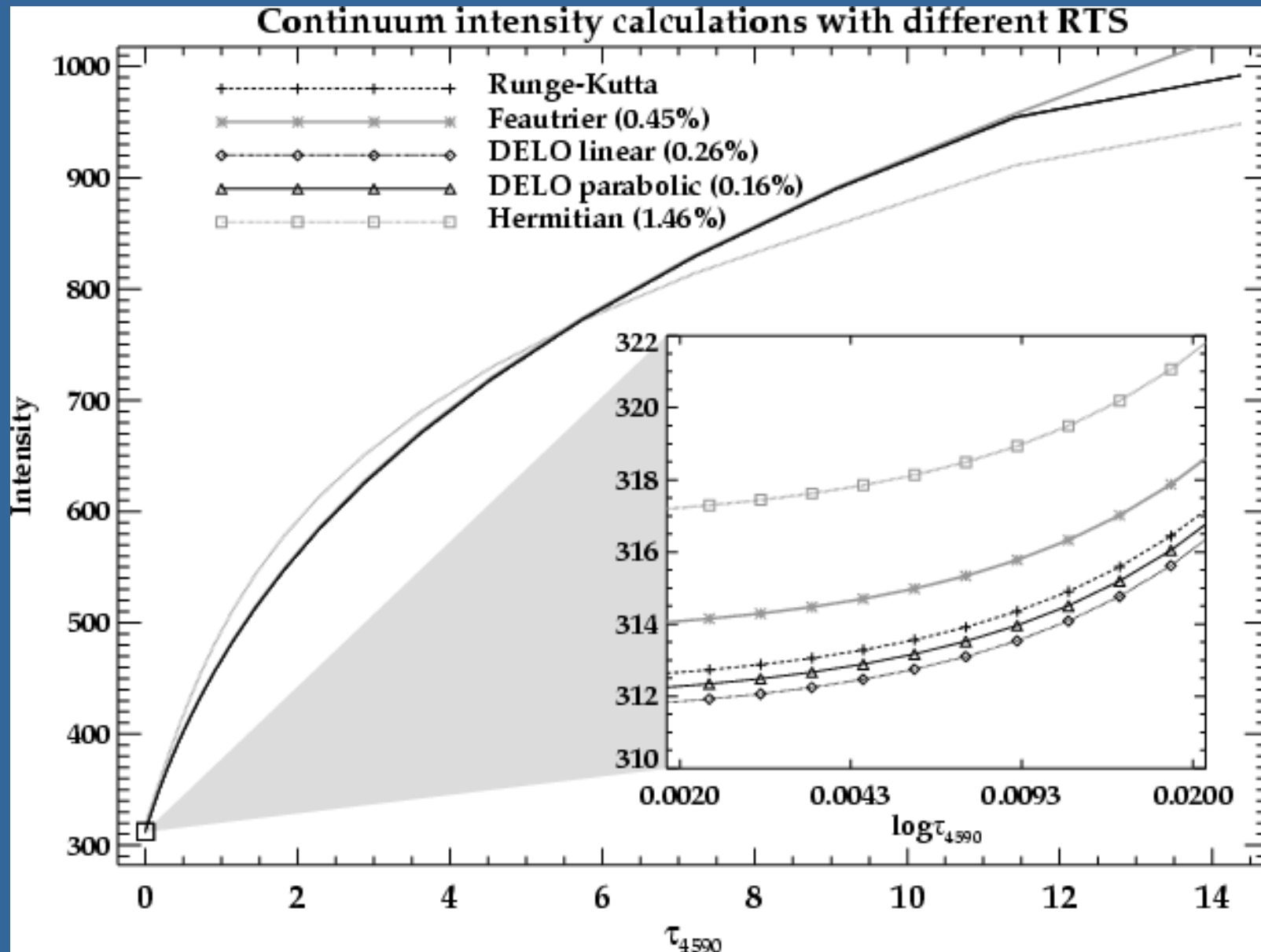
$$I_{i+1} = I_i + \frac{\delta_i}{2} (I'_i + I'_{i+1}) + \frac{\delta_i^2}{12} (I''_i - I''_{i+1})$$

$$I' = k \rho \cdot (I - S)$$

$$I'' = k \rho \cdot [k \rho \cdot (I - S) - S'] + (k \rho)' \cdot (I - S)$$

$$I_{i+1} = \alpha_i \cdot I_i + \beta_i$$

Comparison of the solvers



Home work

Compute spectral synthesis using a method of your choice for a static 1D model atmosphere of the Sun. For a fixed geometrical depth grid and wavelength grid you are given a 2D array of opacities and 2D array of source function. The boundary conditions: no radiation enters through the surface and the flux spectrum at the deepest point is given.